

NAG Toolbox for MATLAB

f11mf

1 Purpose

f11mf solves a real sparse system of linear equations with multiple right-hand sides given an LU factorization of the sparse matrix computed by f11me.

2 Syntax

```
[b, ifail] = f11mf(trans, iprm, il, lval, iu, uval, b, 'n', n, 'nrhs_p',
nrhs_p)
```

3 Description

f11mf solves a real system of linear equations with multiple right-hand sides $AX = B$ or $A^T X = B$, according to the value of the parameter **trans**, where the matrix factorization $P_r A P_c = LU$ corresponds to an LU decomposition of a sparse matrix stored in compressed column (Harwell–Boeing) format, as computed by f11me.

In the above decomposition L is a lower triangular sparse matrix with unit diagonal elements and U is an upper triangular sparse matrix; P_r and P_c are permutation matrices.

4 References

None.

5 Parameters

5.1 Compulsory Input Parameters

1: **trans** – string

Specifies whether $AX = B$ or $A^T X = B$ is solved.

trans = 'N'

$AX = B$ is solved.

trans = 'T'

$A^T X = B$ is solved.

Constraint: **trans** = 'N' or 'T'.

2: **iprm**($7 \times n$) – int32 array

The column permutation which defines P_c , the row permutation which defines P_r , plus associated data structures as computed by f11me.

3: **il**(*) – int32 array

Note: the dimension of the array **il** must be at least as large as the dimension of the array of the same name in f11me.

Records the sparsity pattern of matrix L as computed by f11me.

4: **lval(*) – double array**

Note: the dimension of the array **lval** must be at least as large as the dimension of the array of the same name in f11me.

Records the nonzero values of matrix L and some nonzero values of matrix U as computed by f11me.

5: **iu(*) – int32 array**

Note: the dimension of the array **iu** must be at least as large as the dimension of the array of the same name in f11me.

Records the sparsity pattern of matrix U as computed by f11me.

6: **uval(*) – double array**

Note: the dimension of the array **uval** must be at least as large as the dimension of the array of the same name in f11me.

Records some nonzero values of matrix U as computed by f11me.

7: **b(ldb,*) – double array**

The first dimension of the array **b** must be at least $\max(1, \mathbf{n})$

The second dimension of the array must be at least $\max(1, \mathbf{nrhs_p})$

The \mathbf{n} by $\mathbf{nrhs_p}$ right-hand side matrix B .

5.2 Optional Input Parameters1: **n – int32 scalar**

n , the order of the matrix A .

Constraint: $\mathbf{n} \geq 0$.

2: **nrhs_p – int32 scalar**

Default: The second dimension of the array **b**.

\mathbf{nrhs} , the number of right-hand sides in B .

Constraint: $\mathbf{nrhs_p} \geq 0$.

5.3 Input Parameters Omitted from the MATLAB Interface

ldb

5.4 Output Parameters1: **b(ldb,*) – double array**

The first dimension of the array **b** must be at least $\max(1, \mathbf{n})$

The second dimension of the array must be at least $\max(1, \mathbf{nrhs_p})$

The \mathbf{n} by $\mathbf{nrhs_p}$ solution matrix X .

2: **ifail – int32 scalar**

0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail = 1

On entry, **trans** \neq 'N' or 'T',
or **n** < 0,
or **nrhs_p** < 0,
or **ldb** < max(1, **n**).

ifail = 2

Ill-defined row permutation in array **iprm**. Internal checks have revealed that the **iprm** array is corrupted.

ifail = 3

Ill-defined column permutations in array **iprm**. Internal checks have revealed that the **iprm** array is corrupted.

ifail = 301

Unable to allocate required internal workspace.

7 Accuracy

For each right-hand side vector b , the computed solution x is the exact solution of a perturbed system of equations $(A + E)x = b$, where

$$|E| \leq c(n)\epsilon|L||U|,$$

$c(n)$ is a modest linear function of n , and ϵ is the *machine precision*, when partial pivoting is used.

If \hat{x} is the true solution, then the computed solution x satisfies a forward error bound of the form

$$\frac{\|x - \hat{x}\|_{\infty}}{\|x\|_{\infty}} \leq c(n) \text{cond}(A, x)\epsilon$$

where $\text{cond}(A, x) = \| |A^{-1}| |A| |x| \|_{\infty} / \|x\|_{\infty} \leq \text{cond}(A) = \| |A^{-1}| |A| \|_{\infty} \leq \kappa_{\infty}(A)$. Note that $\text{cond}(A, x)$ can be much smaller than $\text{cond}(A)$, and $\text{cond}(A^T)$ can be much larger (or smaller) than $\text{cond}(A)$.

Forward and backward error bounds can be computed by calling f11mh, and an estimate for $\kappa_{\infty}(A)$ can be obtained by calling f11mg.

8 Further Comments

f11mf may be followed by a call to f11mh to refine the solution and return an error estimate.

9 Example

```
trans = 'N';
iprm = [int32(1);
        int32(0);
        int32(4);
        int32(3);
        int32(2);
        int32(4);
        int32(3);
        int32(1);
        int32(2);
        int32(0);
```

```

        int32(2);
        int32(0);
        int32(8);
        int32(6);
        int32(4);
        int32(4);
        int32(2);
        int32(11);
        int32(8);
        int32(6);
        int32(1);
        int32(2);
        int32(3);
        int32(4);
        int32(5);
        int32(2);
        int32(2);
        int32(2);
        int32(2);
        int32(1);
        int32(1);
        int32(1);
        int32(1);
        int32(2);
        int32(0)];
il = [int32(0);
      int32(1);
      int32(2);
      int32(3);
      int32(-1);
      int32(-1);
      int32(1);
      int32(2);
      int32(3);
      int32(5);
      int32(-1);
      int32(0);
      int32(1);
      int32(2);
      int32(3);
      int32(3);
      int32(3);
      int32(0);
      int32(2);
      int32(4);
      int32(6);
      int32(14);
      int32(8);
      int32(2);
      int32(4);
      int32(6);
      int32(8);
      int32(15);
      int32(0);
      int32(2);
      int32(4);
      int32(6);
      int32(8);
      int32(-1);
      int32(2);
      int32(4);
      int32(6);
      int32(8);
      int32(10);
      int32(0);
      int32(4);
      int32(1);
      int32(4);
      int32(2);
      int32(4);

```

[illegible]

[NP3663/21]

[illegible]

```
uval = [1;  
        3;  
        1;  
        1;  
        0;  
        0;  
        0;  
        0;  
        0;  
        0;
```


[illegible]

```
0;  
0;  
0;  
0;  
0;  
0;  
0;  
0];  
b = [1.56, 3.12;  
     -0.25, -0.5;  
     3.6, 7.2;  
     1.33, 2.66;  
     0.52, 1.04];  
[bOut, ifail] = f11mf(trans, iprm, il, lval, iu, uval, b)  
  
bOut =  
    0.7000    1.4000  
    0.1600    0.3200  
    0.5200    1.0400  
    0.7700    1.5400  
    0.2800    0.5600  
ifail =  
      0
```
